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# **Physics motivation**

# Infinite space-time volume QCD: only parameters quark masses

Other much studied parameters: T, L, v, B,  $\mu$ , ...

Partition function  $Z(T, L, B, v, \mu, ...)$ , observables  $\langle \mathcal{O} \rangle_{T, L, B, v, \mu, ...}$ 

$$\langle \mathcal{O} \rangle_T - \langle \mathcal{O} \rangle_0$$
  $\qquad \qquad \frac{\partial^n}{\partial T^n} \log Z(T) \qquad \qquad \langle \mathcal{O} \rangle_{L,B} - \langle \mathcal{O} \rangle_{L,0}$   $\qquad \qquad L \frac{dg(L)}{dL} \qquad \qquad \frac{\partial^n}{\partial \mu^n} \langle \mathcal{O} \rangle_{\mu}$ 

All introduced in path integral formulation  $\rightarrow$  4D lattice

#### **Physics motivation**

What about rotating QCD matter?

New parameter,  $\omega$  angular velocity,  $Z(\omega)$ ,  $\langle \mathcal{O} \rangle_{\omega}$ 

**STAR:**  $\omega \sim O(10 MeV)$ 

How to do lattice simulations?

Even more basic: continuum path integral formulation?

#### Parameters $\alpha$ coupled to conserved charges Q

$$Z(T,\alpha) = \operatorname{Tr} e^{-\beta(H-\alpha Q)}$$

If  $\alpha = 0$ , path integral formulation as usual

$$H \to \mathcal{L}(\partial_{\mu}\phi(x), \phi(x))$$
  $\phi\left(t + \frac{1}{T}, x\right) = \phi(t, x)$ 

If  $\alpha \neq 0$ , two ways to proceed

$$Z(T,\alpha) = \operatorname{Tr} e^{-\beta(H-\alpha Q)}$$

• Option 1, action modified,  $\mathcal{L}(\alpha) = \mathcal{L}(0) + O(\alpha) + O(\alpha^2)$  same p.b.c.  $\phi(x)$ 

• Option 2, action same,  $\mathcal{L}(\alpha) = \mathcal{L}(0)$  but  $\alpha$  in non-trivial temporal b.c.

Depending on Q one is better/practical/useful the other less so

#### Example, moving frame

Giusti, Meyer, 1011.2727, 1110.3136

Poincare invariant H,  $\alpha = v_k$ ,  $Q = P_k$ 

$$Z(T,v) = \operatorname{Tr} e^{-\beta(H-v_k P_k)}$$

Euclidean setup,  $iv_k = Ty_k$ , in trace we have  $e^{-iy_kP_k}$ 

Option 2, action remains same, modified b.c.

$$\phi\left(t + \frac{1}{T}, \mathbf{x}\right) = \phi(t, \mathbf{x} - \mathbf{y})$$

Well defined continuum path integral, finite T, finite spatial  $\mathbb{T}^3$ 

Shifted boundary condition, can easily simulate, space-time  $\mathbb{T}^4$ 

What about rotation,  $\omega$  ?

Trying the same, Poincare invariant  $H, \quad \alpha = \omega_k, \quad Q = J_k$ 

 $J_k$  generators of SO(3) rotations, infinite spatial volume

#### Try the same

$$Z(T,\omega) = \operatorname{Tr} e^{-\beta(H-\omega_k J_k)}$$

First problem: rigid rotation in infinite volume not okay

Must have finite volume, spatial  $\mathbb{T}^3$ 

Second problem: on  $\mathbb{T}^3$  no SO(3) symmetry, no  $J_k$ 

Euclidean setup,  $i\omega_k = T\vartheta_k$ 

No infinitesimal generators, but finite  $U(\vartheta)$  unitary operator

$$Z(T, \vartheta) = \operatorname{Tr} e^{-\beta H} U(\vartheta)$$

$$Z(T,\vartheta) = \operatorname{Tr} e^{-\beta H} U(\vartheta)$$

Turn it into path integral (without rotations:  $\mathbb{T}^4$  space-time)

With  $\vartheta \neq 0$ , choose option 2

 $\mathcal{L}(\vartheta) = \mathcal{L}(0)$  same action as before

Put  $\vartheta$  into boundary condition

Rotated boundary conditions: periodic up to rotation

#### Rotated boundary conditions

Clearly not all  $\vartheta$  allowed, only some discrete values

Note: "periodic up to rotation" means space-time is not  $\mathbb{T}^4$ 

2 dimensional analogy:  $\mathbb{T}^2$ , Mobius-band, Klein-bottle

Still flat, compact, orientable, smooth 4-manifold

There are 26 topologically different non-trivial flat, compact, orientable 4-manifolds

# Rotated boundary conditions

All 26 look like  $\mathcal{M}=\mathbb{T}^4/G$  with finite  $G\subset E(4)=SO(4)\ltimes\mathbb{R}^4$  Euclidean group G one of

$$\mathbb{Z}_{2,3,4,6}$$
  $\mathbb{Z}_2 \times \mathbb{Z}_2$   $D_{6,8,12}$   $A_4$ 

Some abelian, some non-abelian

Shift around time is translation, followed by rotation, together in Euclidean group

#### Rotated boundary conditions

Fun fact: this was the original motivation:)

Shifted b.c.: periodic up to shift  $\rightarrow$  shift element of Poincare  $\rightarrow$  other elements

of Poincare: rotations  $\rightarrow$  periodic up to rotation?

What kind of b.c. are these??

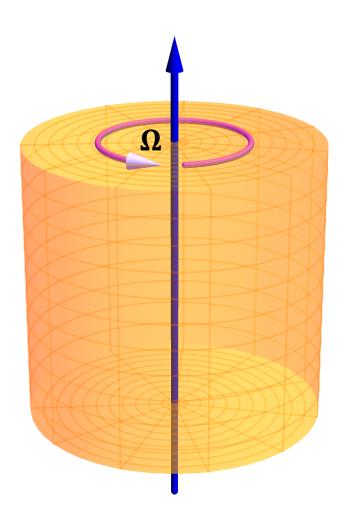
Very non-trivial to get all consistent such b.c. by hand

Classification up to 6D possible

Some of 26 do have rotating frame interpretation

What did people do before?

# What did people do before?



What did people do before?

# Finite cylindrical slab

Introduce rotation by going to rotating frame

Chernodub, Gongyo 1611.02598

$$(t, x, y, z) = (t, r \cos \phi, r \sin \phi, z)$$
  $\tilde{\phi} = \phi - \omega t$ 

$$g_{\mu\nu}(x) = \begin{pmatrix} 1 - (x^2 + y^2)\omega^2 & y\omega & -x\omega & 0\\ y\omega & -1 & 0 & 0\\ -x\omega & 0 & -1 & 0\\ 0 & 0 & 0 & -1 \end{pmatrix}$$

Lagrangian in curved space-time,  $\mathcal{L}(\omega)$ , option 1.

What did people do before?

Why is this not ideal?

Temporal b.c. the same as before, but b.c. on the cylinder?

Discretization awful, breaks SO(2), curved space, continuum limit?, ...

Negative moment of inertia?

Our setup: flat space, spatial b.c. straightforward, easy to discretize

Minor changes relative to  $\omega = 0$ 

Compact, flat, orientable 4-manifolds

Beyond topological classification, need to classify flat metrics on  $\mathcal{M} = \mathbb{T}^4/G$ 

These come from flat metrics on  $\mathbb{T}^4$ 

First classify flat metrics on  $\mathbb{T}^4$  – very easy

See which are compatible with action of G

# Compact, flat, orientable 4-manifolds

# Flat metrics on $\mathbb{T}^4$

 $\mathbb{T}^4 = \mathbb{R}^4/\Lambda$  with lattice  $\Lambda \subset \mathbb{R}^4$  defined by basis vectors  $e^a$ 

$$\Lambda = \left\{ \sum_{a=0}^{3} n_a e^a \mid n_a \in \mathbb{Z} \right\}$$

Standard flat metric on  $\mathbb{R}^4$ 

$$\mathcal{M} = \mathbb{T}^4/G = \mathbb{R}^4/(G \ltimes \Lambda) \qquad G_{\Lambda} = G \ltimes \Lambda$$

# Compact, flat, orientable 4-manifolds

Usual 
$$\mathbb{T}^4$$
:  $|e^0| = \frac{1}{T}$  and  $|e^{1,2,3}| = L$  and orthogonal

Will need non-orthogonal  $\mathbb{T}^4$  too

4 vectors into 
$$4 \times 4$$
 matrix  $e = (e^1|e^2|e^3|e^4)$ 

Flat metric on  $\mathcal M$  fully determined by e and G, topology by  $G_{\Lambda}$ 

$$vol(\mathcal{M}) = \frac{|\det(e)|}{|G|}$$
  $\pi_1(\mathcal{M}) = G_{\Lambda}$ 

Main task: for each  $G_{\Lambda}$  find most general e

Look at first  $G = \mathbb{Z}_k$  with k = 2, 3, 4, 6 (non-abelian or  $\mathbb{Z}_2 \times \mathbb{Z}_2$  also possible)

Rotation by 
$$\vartheta = \frac{2\pi}{k}$$

Choose metrics,  $GL(4,\mathbb{Z})$  and SO(4) freedom

$$e = \left(\begin{array}{cc} L_0 & 0\\ 0 & E \end{array}\right)$$

With E a 3 × 3 matrix  $E = (E^1|E^2|E^3)$ , defining spatial  $\mathbb{T}^3$ 

 $G = \mathbb{Z}_k$  defined by generator g = (A, b) where  $A \in SO(4)$  and  $b \in \mathbb{R}^4$ 

$$A = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos(2\pi/k) & -\sin(2\pi/k) & 0 \\ 0 & \sin(2\pi/k) & \cos(2\pi/k) & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \qquad b = \begin{pmatrix} L_0/k \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Clearly 
$$g^k = 1$$
 and  $T = \frac{k}{L_0}$ 

Two topologically different k = 2, 3, 4 and single k = 6

$$G = \mathbb{Z}_{2,3,4,6}$$
 and  $G = \mathbb{Z}'_{2,3,4}$ 

No other k possible

#### **Boundary conditions**

$$\phi\left(t + \frac{L_0}{k}, x_1, x_2, x_3\right) = \phi(t, x_1', x_2', x_3) \qquad \phi(t, x + E^a) = \phi(t, x)$$

$$x_1' = x_1 \cos(2\pi/k) + x_2 \sin(2\pi/k)$$

$$x_2' = -x_1 \sin(2\pi/k) + x_2 \cos(2\pi/k)$$

Rotated in temporal direction, periodic spatially

Very easy to implement on lattice

Need to specify metrics E for each case,  $G = \mathbb{Z}_{2,3,4,6}$  and  $G = \mathbb{Z}'_{2,3,4}$ 

$$E(\mathbb{Z}_2) = \frac{L}{|z_2 z_3|^{1/3}} \begin{pmatrix} 1 & 0 & 0 \\ z_1 & z_2 & 0 \\ 0 & 0 & z_3 \end{pmatrix} \qquad E(\mathbb{Z}_3) = L \left(\frac{\sqrt{3}}{2|z|}\right)^{1/3} \begin{pmatrix} 1 & 0 & 0 \\ \frac{1}{\sqrt{3}} & \frac{2}{\sqrt{3}} & 0 \\ 0 & 0 & z \end{pmatrix}$$

$$E(\mathbb{Z}_4) = \frac{L}{|z|^{1/3}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & z \end{pmatrix} \qquad E(\mathbb{Z}_6) = E(\mathbb{Z}_3)$$

z parameters continuous, dimensionless, arbitrary,  $vol(\mathbb{T}^3) = |\det(E)| = L^3$ 

$$E(\mathbb{Z}_2') = \frac{L}{(2|z_2z_3|)^{1/3}} \begin{pmatrix} z_1 & -z_1 & z_3 \\ z_2 & -z_2 & 0 \\ 1 & 1 & 0 \end{pmatrix} \qquad E(\mathbb{Z}_3') = L \frac{2^{1/3}}{|z|^{1/3}\sqrt{3}} \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 1 \\ -\frac{\sqrt{3}}{2} & \frac{\sqrt{3}}{2} & 0 \\ -z & -z & z \end{pmatrix}$$

$$E(\mathbb{Z}_4') = \frac{L}{|z|^{1/3}} \begin{pmatrix} 1 & 0 & \frac{1}{2} \\ 0 & 1 & \frac{1}{2} \\ 0 & 0 & z \end{pmatrix}$$

Correspond to all possible rotations of a parallelopiped by  $\vartheta = \frac{2\pi}{k}$ 

Note: orthogonal  $\mathbb{T}^3$  possible with k = 2, 3, 4 (not k = 6)

For k = 6 angles:  $(90^{\circ}, 60^{\circ}, 60^{\circ})$ 

#### Summary

Defined QFT,  $Z(\omega)$ , on rotating box at finite T in path integral formulation

Action same as before, rotated boundary conditions

Imaginary  $\omega$  not arbitrary but 4 discrete values

Space-time still flat, spatially periodic

Easy to discretize and do lattice, clear continuum limit

Easy to compare with  $\omega = 0$ 

Can also introduce moving frame  $y = (0, 0, y_3)$ 

#### Summary

Gauge theory straightforward

**All 7** have spin structure → fermions

Opens door to lattice simulations

Can address negative moment of inertia?

Only 7 compact, flat, orientable manifolds, there are 19 more (16 spin)

Lots of other applications beyond rotating box

Thank you for your attention!

#### Outlook

## Finite volume effects on $\mathbb{T}^3$

If orthogonal:  $\sim e^{-mL}$ 

If not orthogonal:  $\sim e^{-\alpha mL}$  with  $\alpha>1$  possible

**Exponentially smaller finite volume effects** 

Largest 
$$\alpha = 2^{1/6}$$

 $\alpha > 1$  can be realized with all k = 2, 3, 4, 6